Software Development

LAPS Workshop Oct 25-27, 2010

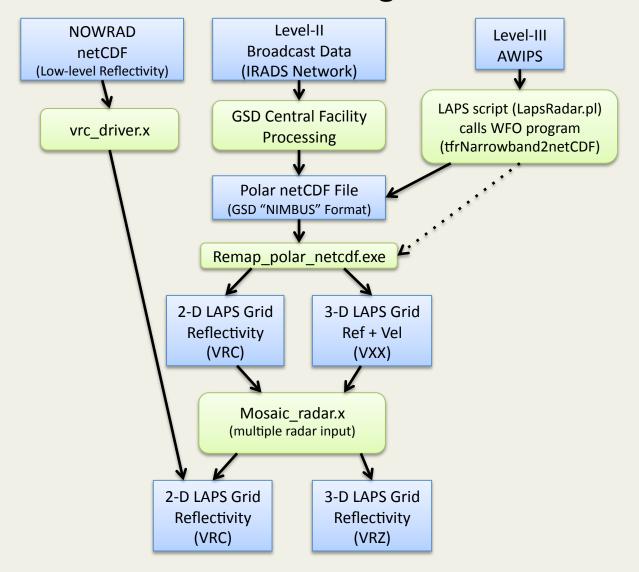
More info (including Forum) at:

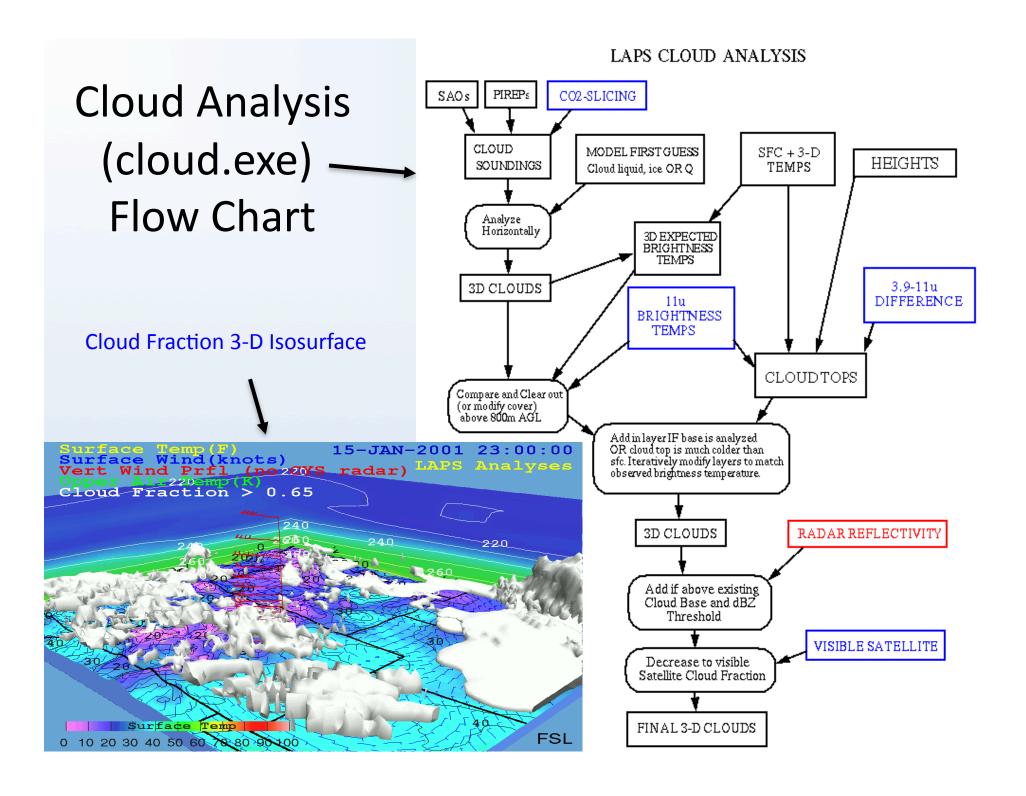
http://laps.noaa.gov

	LAPS README		2.6I/O of LAPS gridded files
	LAI S KEADNIE		2.7CHANGING THE HORIZONTAL DOMAIN
			2.7.1Number of Grid Points
	This LAPS/STMAS README file is viewable on the WWW via the LAPS hon	ne nage	2.7.2Location of Domain (Map projections)
	This bit is to think the terminal of the transfer of the trans	ne page	2.7.2.1MAP PROJECTION FUNCTIONALITY/LIMITATIONS
	TABLE OF CONTENTS		2.7.3 Domain Resolution
	TIBLE OF CONTENTS		2.7.4 Terrain Smoothing/Filtering
	1.0 General LAPS info		2.8CHANGING THE VERTICAL DOMAIN
	1.1LAPS Software Disclaimer		2.8.1Sigma Height Grid
			2.8.2Sigma Pressure Grid
1	2.0 Installing and running the LAPS Ingest/Analysis code		2.9 CHANGING THE CYCLE TIME
2.1	2.1UNIX System Requirements		2.10LQ3 (HUMIDITY ANALYSIS) CHANGES
	2.1.1 NetCDF library		2.11OTHER RUNTIME PARAMETERS
	2.1.2Perl		2.12 Detecting and Reporting Installation Errors
	2.1.3 make		2.12.1Runtime Monitoring
	2.1.4 C Compiler	2 4	3.0 Description of LAPS Processes
	2.1.5FORTRAN Compiler	3.1	3.1Localization Processes
	2.1.6 Disk Space		3.1.1 Gridgen model (static.nest7grid generation)
	2.1.7 Memory Etc. (ulimit)		3.1.2 Surface Lookup Tables (gensfclut.exe)
		\mathbf{r}	3.1.3 Satellite Lookup Tables (genlvdlut.exe)
	2.1.8.1 Web Display	3.2	3.2Ingest Processes
	2.1.9 GRIB2 external libraries (optional)		3.2.1LGA Model
2.2			3.2.2 Surface Data Ingest
Z.Z	2.2Installation Procedure Summary		3.2.2.1 obs driver.x
	2.2.1Untarring the Source Code		3.2.2.2sfc qc.exe
	2.2.2Running Configure		3.2.2.3
	2.2.2.1 Modifying Compiler Flags		3.2.3
	2.2.3 Ingest Software changes		3.2.4
	2.2.4Running make		3.2.5
	2.2.5Geography databases		3.2.6
	2.2.6 Localizing for single or multiple data domains		3.2.8
	2.2.6.1Localization Method 1		3.2.9Sounding (RAOB/Dropsonde/Sat/Radiometer) (SND) Ingest
	2.2.6.2 Localization Method 2		3.2.10LVD (Satellite Image + Cloud Top Pressure)
	2.2.6.3 Localization with LAPS GUI		3.2.11
	2.2.7WRF Domain Wizard LAPS Support	3.3	3.3 ANALYSIS PROCESSES
		J.J	3.3.1WIND
2	2.2.8MPI support for LAPS wind analysis		3.3.2 SFC (LSX)
2.3	2.3Raw data ingest		3.3.2.1 SURFACE ANALYSIS RUNTIME PARAMETERS
	2.3.1 Model Background (lga/lgb)		3.3.2.2 SURFACE ANALYSIS QUALITY CONTROL
	2.3.1.1 Acquiring Model Background Data		3.3.2.3 SURFACE ANALYSIS VERIFICATION
	2.3.2Radar ingest		3.3.2.4 STMAS-2D
	2.3.3 Surface Data		3.3.3TEMP
	2.3.4Wind Profiler / RASS		3.3.4CLOUD
	2.3.5 PIREPS & ACARS from aircraft		3.3.5WATER VAPOR (HUMIDITY PROCESSING)
	2.3.6RAOB / Dropsonde / Radiometer		3.3.6DERIV
	2.3.7 Satellite		3.3.7 ACCUM
	2.3.8 GPS		3.3.8 SOIL MOISTURE
	2.3.9 Other Data Sources		3.3.9 BALANCE
			3.3.10STMAS3D
MOSPHED		3.4	3.4 Model Initialization & Postprocessing
ALC AD.	2.4.1 Cron timing considerations	•	3.4.1LAPSPREP
AA 💦	2.4.2Purging Output Files		3.4.2LAPS2GRIB
TRA	2.4.3 STMAS and other configurations		3.4.3WFOPREP
No.	2.5 Test data case	1.0	3.4.4LFMPOST
	2.5.1 Analysis Only Test		4.0 Porting code mods from LAPS users back to GSD
T OF COMM.	2.5.2 Ingest + Analysis Test	5.0	5.0 LAPS Output Variables and netCDF File Organization

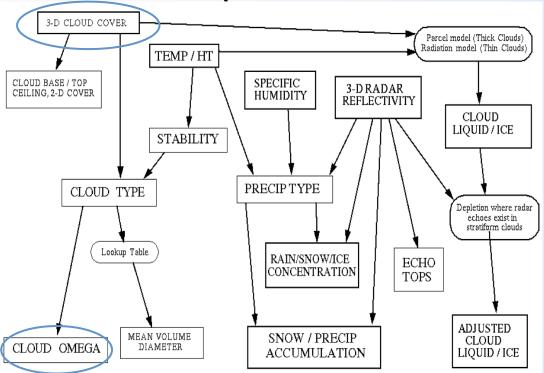
П

LAPS Radar Ingest





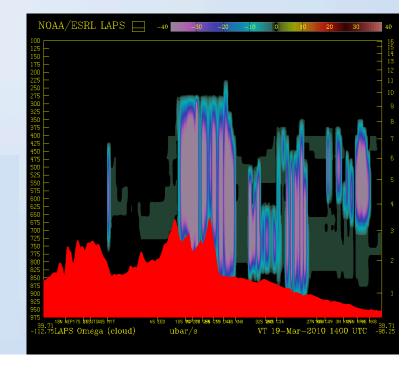
Microphysics, Vertical Motion and Hot-Start (deriv.exe + accum.exe)



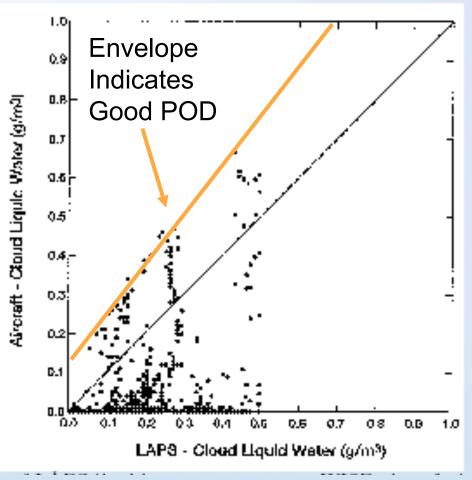
Dramatically improves
Very short-range forecast,
Importance to terminal
Scale forecasts

LAPS hot-start scheme

The hot-start scheme will be adapted into STMAS, a multi-grid variational data assimilation system with satellite, radar, conventional obs and model dynamic constraint applied simultaneously.



Analyzed Cloud Liquid vs WISP Aircraft measurements



Scatter (FAR) due to unresolved small-scale LWC variability, otherwise good analysis of icing potential

Balance Package

User-defined weights O

$$J = \sum_{k} \sum_{j} \sum_{i} O_{V} (\hat{u} - u')^{2} + O_{V} (\hat{v} - v')^{2} + O_{\omega} (\hat{\omega} - \omega_{c}')^{2} + O_{\Phi} (\hat{\Phi} - \Phi')^{2}$$

$$+ \mu (\hat{u}_{t})^{2} + \mu (\hat{v}_{t})^{2} + \lambda (\hat{u}_{x} + \hat{v}_{y} + \hat{\omega}_{p})$$

$$+ B_{V} \hat{u}^{2} + B_{V} \hat{v}^{2} + B_{\Phi} \hat{\Phi}^{2} + B_{\omega} \hat{\omega}^{2}$$
Eqn 1

Hatted quantities: solution increment

Primed quantities: pre-balanced increment

(observations), **B** (background) are defined from known error characteristics of the first stage analysis and background model, respectively. Ideally **B** represents the actual error statistics fror the background model. Weight μ adjusts the magnitude of the residual Eularian time tendencies of u and v relative to the other constraints and provides a balance among the mass and momentum fields. The term λ is a Lagrange multiplier that becomes another unknown. λ will

ensure that continuity is satisfied to the limits of computational accuracy.

The Eulerian time tendencies u_t and v_t given below in Eqn. 2a and b,

utilize background ()_b fields so the non-linear terms become quasi-linearized with known estimates from the previous analysis step. Subscripts x, y, and p refer to horizontal (x,y) and vertical (p) derivatives.

$$\hat{u}_{t} = -(u_{b}\hat{u}_{x} + \hat{u}u_{bx} + v_{b}\hat{u}_{y} + \hat{v}u_{by} + \omega_{b}\hat{u}_{p} + \hat{\omega}u_{bp}) - \hat{\Phi}_{x} + f\hat{v} - D(\hat{u})$$
 Eqn 2a

$$\hat{v}_{t} = -(u_{b}\hat{v}_{x} + \hat{u}v_{bx} + v_{b}\hat{v}_{y} + \hat{v}v_{by} + \omega_{b}\hat{v}_{p} + \hat{\omega}v_{bp}) - \hat{\Phi}_{y} - f\hat{u} - D(\hat{v})$$
 Eqn 2b

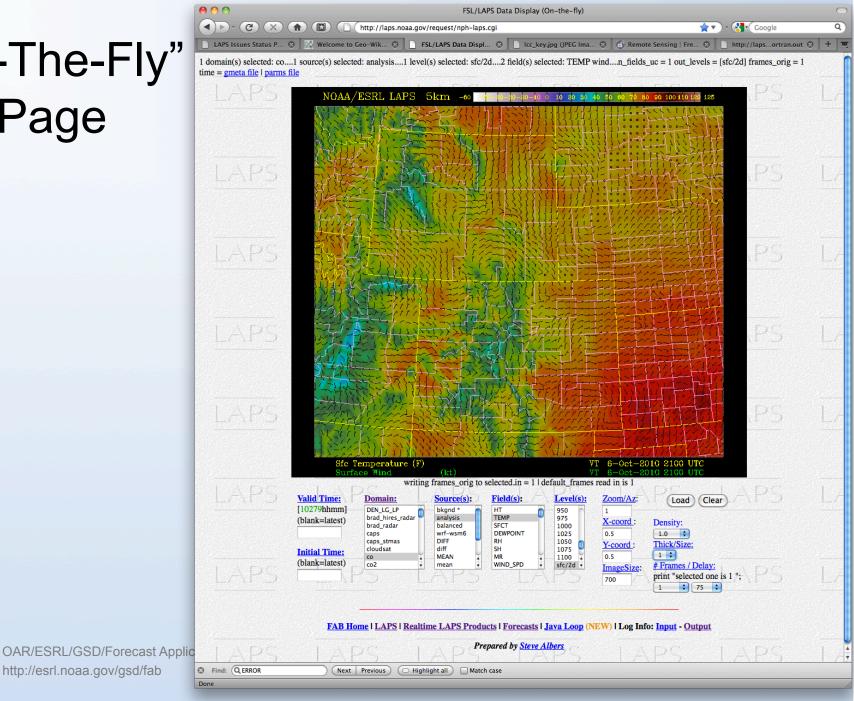
Future Cloud Analysis Development

- Higher Resolution Time/Space
- Develop forward models for all data sources being used to more fully implement a variational approach
- Incorporate methodologies into STMAS & GSI
- Consider new data sources (e.g. airborne radar)
- Improve rain gauge / radar / model first guess blending for QPE

Web Products

- NCL/NCAR graphics based
- Pre-Generated NCAR graphics
 - "Sched.pl –f" runs followup_ncarg.sh to generate GIF images
- "On-the-fly" page
 - "nph-laps.cgi" script (etc/www) directory
 - Can be run on a web server
 - Publication quality imagery
 - Horizontal, vertical cross sections, soundings
 - Verify/overlay model forecasts with analyses and observations
 - Difference plots (e.g. analysis vs. first guess)
 - Animations (animated GIF / Java)
 - Montages (e.g. ensemble display through time)

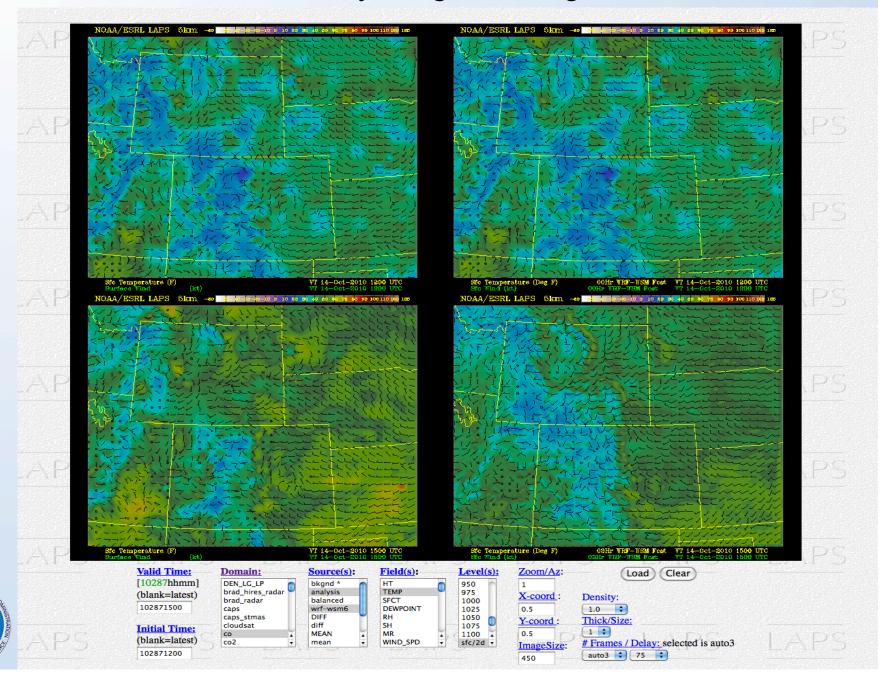
"On-The-Fly" Page

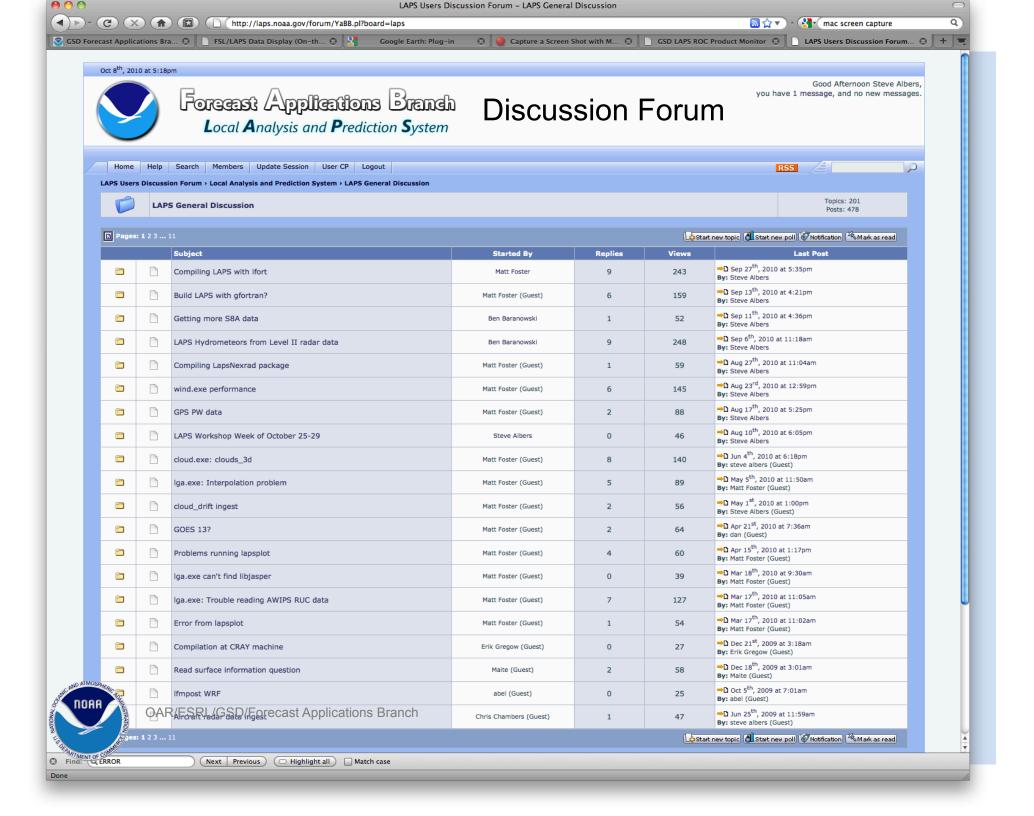




http://esrl.noaa.gov/gsd/fab

"On-the-fly" Page Montage





Analysis software plans

- Portability
 - Intel/ifort
 - GFORTRAN
 - Mac (Linux)
- Parallelization
 - MPI works with Traditional LAPS wind analysis
 - STMAS minimization routine is next.
 - GPU technology
- Optimize & Vectorize serial code
- Sub-Kilometer resolution
 - Hi-res Terrain / Land Use (incorporated in balancing constraints)

Thanks!

More info at:

http://laps.noaa.gov

Questions / Comments?